

Mathe-Grundlagen

1. Totale Ableitung von f(x,y) mit mehreren Variablen

Beispiel: $f(x,y) = x^2 y$
 $f(x(t), y(t)) = t^6 (t+5)$
 $= t^7 + 5t^6$

$$x = t^3$$
$$\frac{dx}{dt} = 3t^2$$

$$y = t + 5$$
$$\frac{dy}{dt} = 1$$

$$\frac{df}{dt} = 7t^6 + 30t^5$$
$$= \left(\frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt} \right)$$
$$= 2xy \cdot 3t^2 + x^2 \cdot 1$$
$$= 2t^3(t+5) \cdot 3t^2 + t^6$$
$$= 6t^6 + 30t^5 + t^6$$

Aufgabe:

$$f(x,y) = x^3 y$$

$$x = t^2$$

$$y = t^3 + 2t$$

Ableitungs-Schreibweisen $\frac{df}{dt} = \dots$

$$\dot{s} = s'(t) = \frac{ds}{dt}$$

$$\frac{df}{dt} = \frac{f}{x} \cdot \frac{dx}{dt} + \frac{f}{y} \cdot \frac{dy}{dt}$$

$$| \cdot dt$$

$$df = \frac{f}{x} \cdot dx + \frac{f}{y} \cdot dy$$

$$f_2 - f_1 = \int_{x_1}^{x_2} \frac{f}{x} dx + \int_{y_1}^{y_2} \frac{f}{y} dy$$

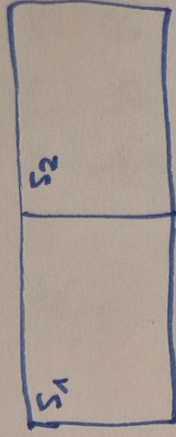
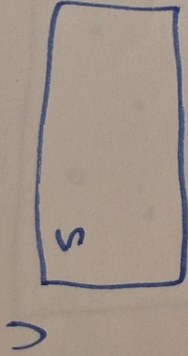
$$\frac{d \ln(x) \eta}{dt} = \frac{1}{x} \cdot \frac{dx}{dt} \cdot \eta$$

$$| \cdot dt$$

$$\frac{d \ln(x)}{dt} = \frac{1}{x} \cdot \frac{dx}{dt}$$

$$\ln(x) = b$$

Grundbegriffe der Thermodynamik



oder

1. Hauptsatz
des TD

$$dU = \delta Q - \delta W$$

innere
Energie

Wärme

Arbeit

$$dU = T \cdot dS - p \cdot dV$$

Temperatur

Entropie

Druck

Volumen

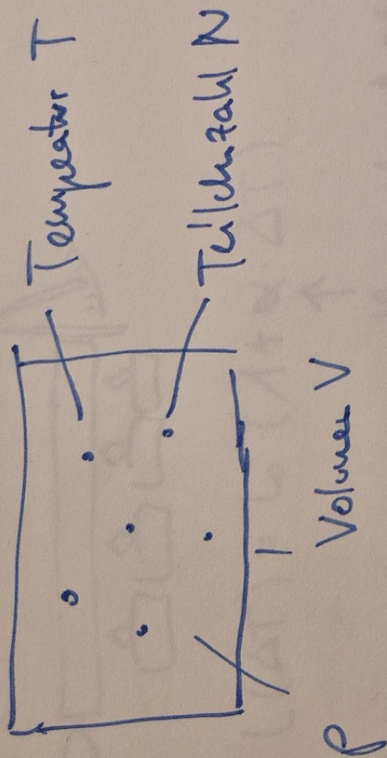
Exensive Größe	Intensive Größe
V	p
S	T

thermische Energie

mechanische Energie

↖ Zustandsgrößen

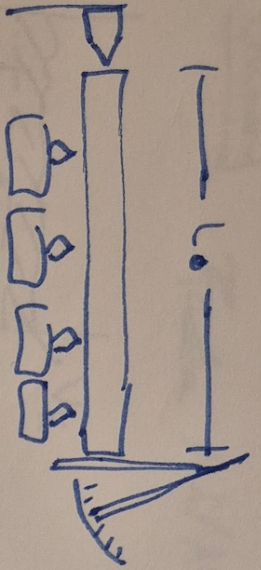
Idealer Gas



p	V	$=$	N	k_B	T
		$=$	N	R	T
		$=$	N	R_s	T

$$\frac{N}{N} = \frac{N}{N}$$

Thermische Ausdehnung



$$l(\Delta T) = l_0 \cdot (1 + \alpha \cdot \Delta T)$$

$$V(\Delta T) \approx V_0 (1 + 3 \cdot \alpha \cdot \Delta T)$$

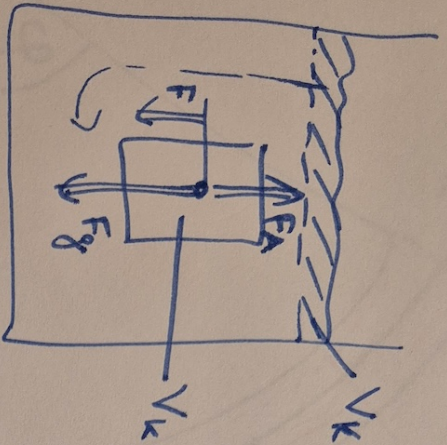
lineare thermischer Ausdehnungskoeffizient

$$V(\Delta T) = V_0 (1 + \gamma \cdot \Delta T)$$

kubisch thermische Ausdehnungskoeffizient

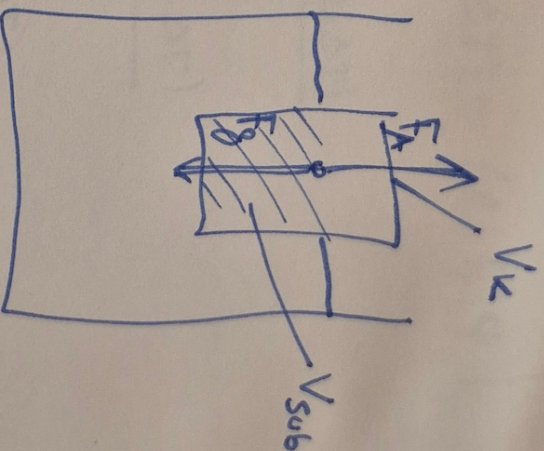
Ermittlung

~~Fach~~ Auf/Abtrieb

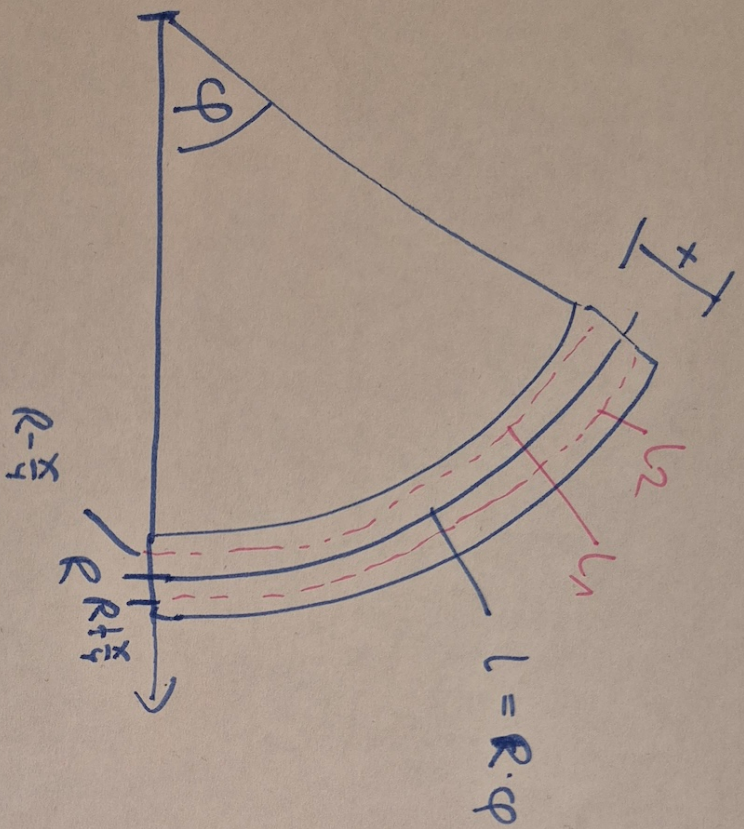


$$\begin{aligned}
 F &= F_g - F_A \\
 &= m_g \cdot g - m_w \cdot g \\
 &= \rho_k V_k \cdot g - \rho_w \cdot V_k \cdot g \\
 &= (\rho_k - \rho_w) V_k \cdot g \\
 &= \left(1 - \frac{\rho_w}{\rho_k}\right) \cdot \rho_k \cdot V_k \cdot g \\
 &= \left(1 - \frac{\rho_w}{\rho_k}\right) \cdot m_k \cdot g
 \end{aligned}$$

Schwinnen



$$\begin{aligned}
 F_g &= F_A \\
 m_k \cdot g &= m_w \cdot g \\
 \rho_k \cdot V_k \cdot g &= \rho_w \cdot V_{sub} \cdot g \\
 \frac{V_k}{V_{sub}} &= \frac{\rho_w}{\rho_k}
 \end{aligned}$$



$$l_1 = \left| l_0 (1 + \alpha_1 \Delta T) = (R - \frac{x}{4}) \varphi \right|$$

$$l_2 = \left| l_0 (1 + \alpha_2 \Delta T) = (R + \frac{x}{4}) \varphi \right|$$

$$\varphi = \frac{l_0 (1 + \alpha_1 \Delta T)}{R - \frac{x}{4}}$$

$$\varphi = \frac{l_0 (1 + \alpha_2 \Delta T)}{R + \frac{x}{4}}$$

$$R = \frac{x}{4} \frac{2 + (\alpha_1 + \alpha_2) \Delta T}{(\alpha_2 - \alpha_1)}$$

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